

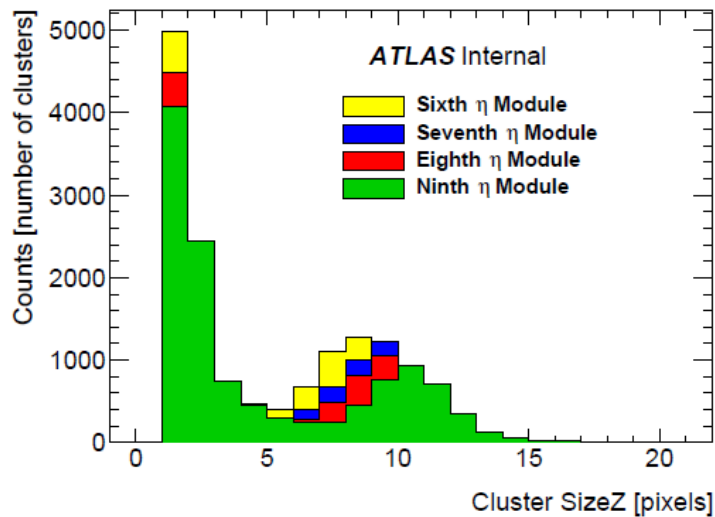
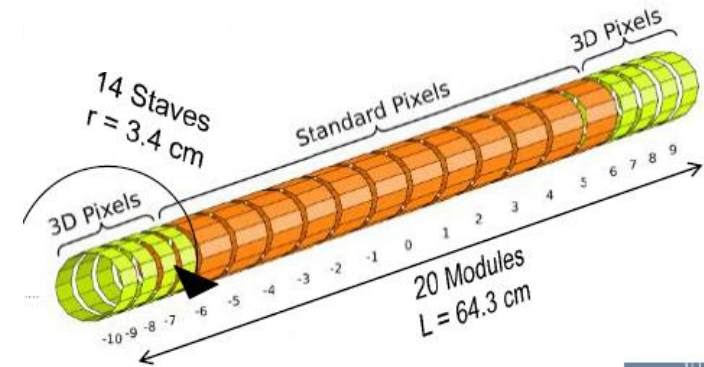
# Status of the Pixel-Cluster Counting Luminosity Measurement

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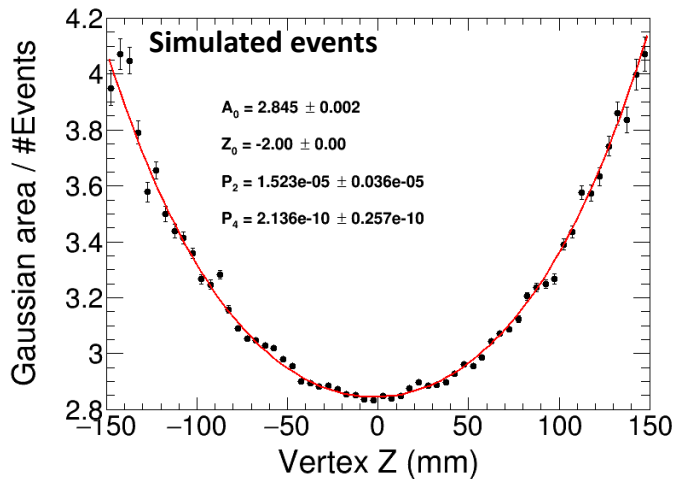
# Pixel Cluster Counting (PCC) in IBL

- The luminosity is proportional to the number of pixel clusters
- Only count the clusters in 3D modules in IBL to get better S-B separation



# Dependence on beamspot shape

- The number of pixels in the 3D sensors in IBL depends on the interaction location  $\leftarrow$  different acceptance



(interaction position x and y are well constrained)

- The number of pixel clusters in all 3D sensors produced by the interaction at Z

$$= A_0 * (1 + p_2 * (z - z_0)^2 + p_4 * (z - z_0)^4)$$

**Obtained with the study of simulated single interaction events**

(  $z_0$  is the IBL center.  $z_0 = -2\text{mm}$  in the simulated samples )

- The interaction vertices density in Z is  $\text{Gauss}(Z; \mu_z, \sigma_z) \sim \text{beamspot}$
- The total number of pixel clusters produced by all interactions
 
$$= \int A_0 * (1 + p_2 * (z - z_0)^2 + p_4 * (z - z_0)^4) * \text{Gauss}(z, \mu_z, \sigma_z) dz$$

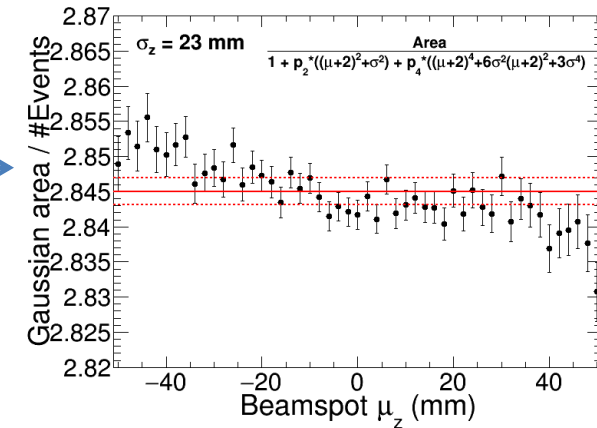
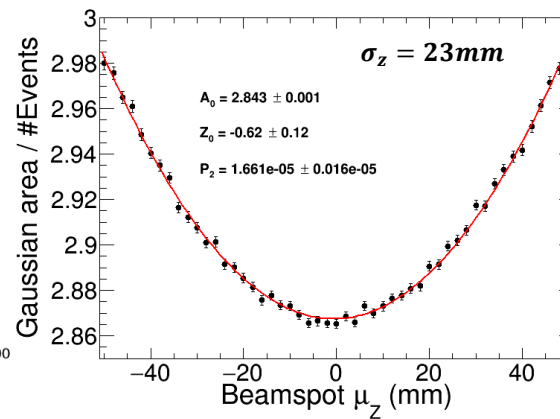
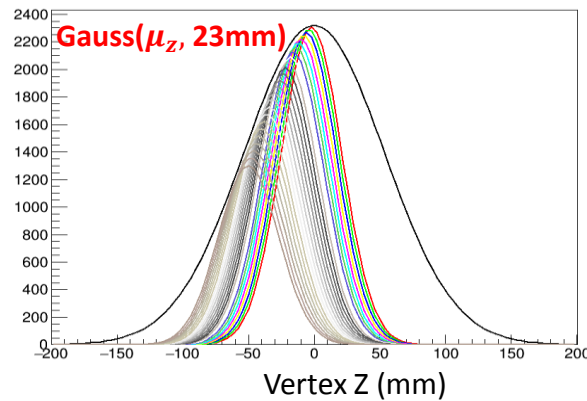
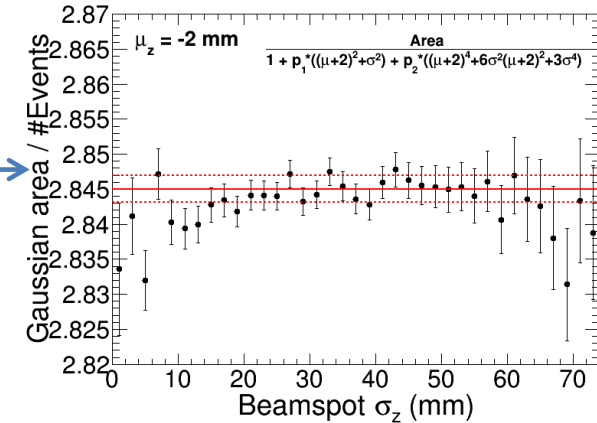
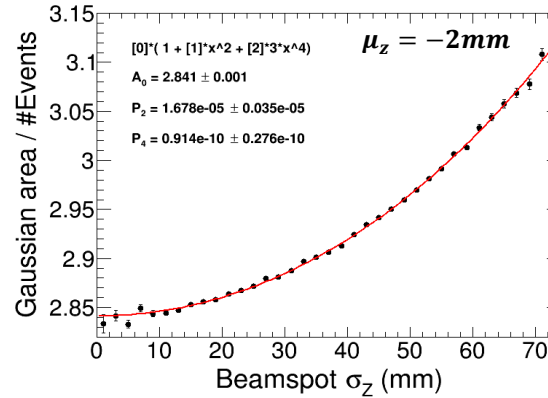
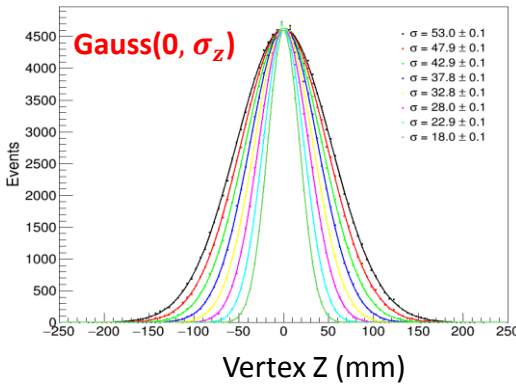
$$= A_0 * \left[ 1 + p_2 * \left( (\mu_z - z_0)^2 + \sigma_z^2 \right) + p_4 * \left( (\mu_z - z_0)^4 + 6\sigma_z^2(\mu_z - z_0)^2 + 3\sigma_z^4 \right) \right]$$

❖ The obtained area should be corrected to be  $A_0$  which only depends on  $\langle \mu \rangle$

# Correction of the beamspot shape dependence

- The area obtained with beamspot  $\sim \text{Gauss}(\mu_z, \sigma_z)$  should be corrected via:

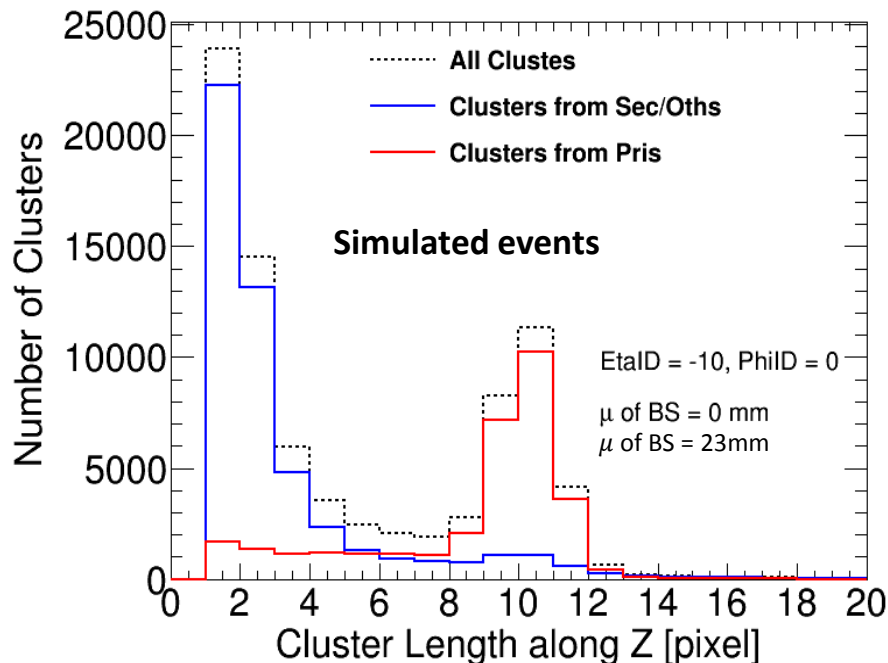
$$A_0 = \frac{\text{Area}}{1 + p_2 * ((\mu_z - z_0)^2 + \sigma_z^2) + p_4 * ((\mu_z - z_0)^4 + 6\sigma_z^2(\mu_z - z_0)^2 + 3\sigma_z^4)}$$



- ❖ After the correction, the number of clusters obtained from any beamspot shape is consistent with the expected  $A_0$

# Counting truth → Fitting

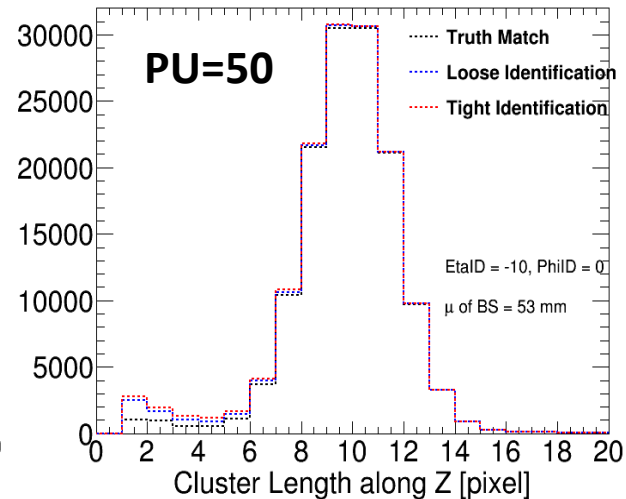
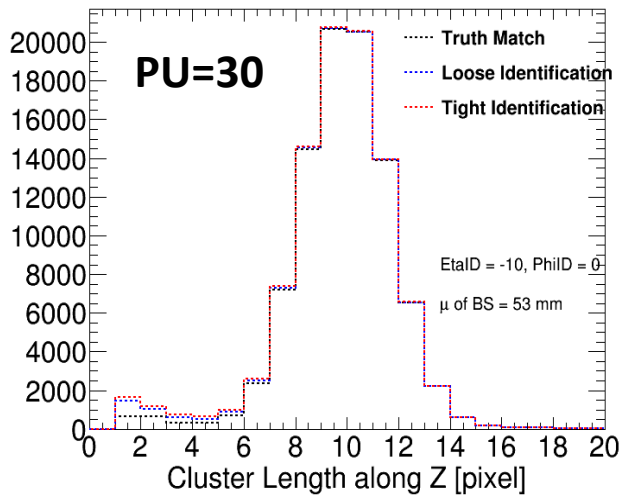
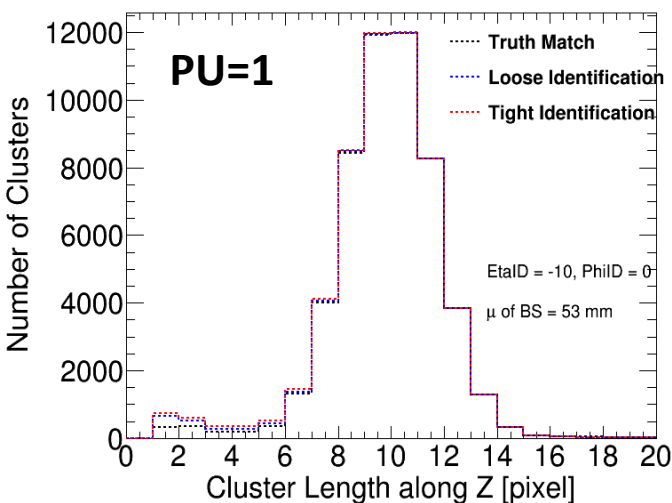
- The study of MC is performed by counting the clusters from primary particles
- The number of clusters only could be obtained by fitting in the real data due to the bkg
  - Secondary particles are from the interaction of primaries with the material (barcode > 200000)
    - Others: some secondary particles do not have truth information stored for space reasons.
  - “Afterglow”: delayed tails of the particle cascade produced in the detector material (not in MC)



- The cluster length of clusters from primary particles (barcode < 200000) are supposed to be a Gaussian
  - Gaussian shape of beamspot
- ✓ Flat tail of the clusters from primary particles
  - Clusters on the module edge
  - Broken clusters
- ❖ Easy to know which clusters are on the edge, but *how to identify the broken clusters?*

# Identification of broken clusters

- **Truth Match**
  - There are other clusters from the same matched truth particles
- **Tight ( Loose ) Identification independent of truth information**
  - There are other clusters with one pixel gap along Z relative to this cluster, and some of their hits are in the same ( or adjacent ) rows



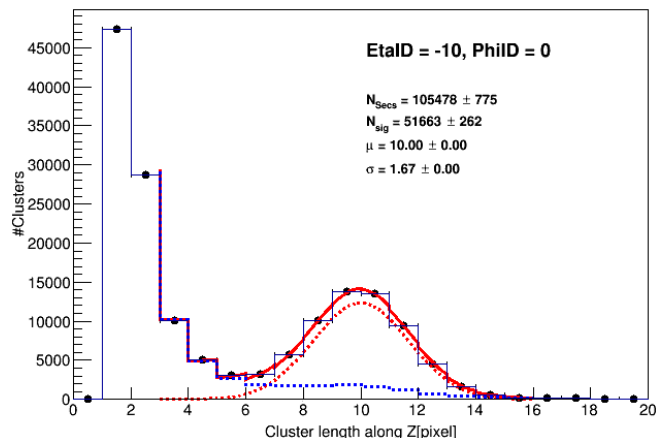
✓ Simulated events, Beamspot  $\sim \mu_z = 0, \sigma_z = 53mm$

❖ **This identification method works even for high pile-up events**

But there are still some clusters in flat tail. Gaussian shape could give it a good description?

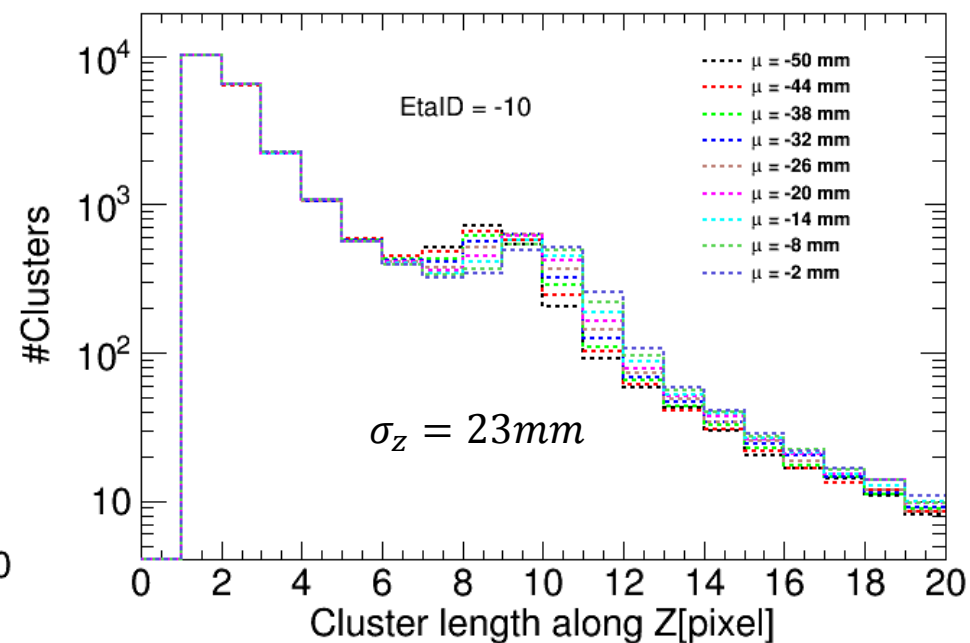
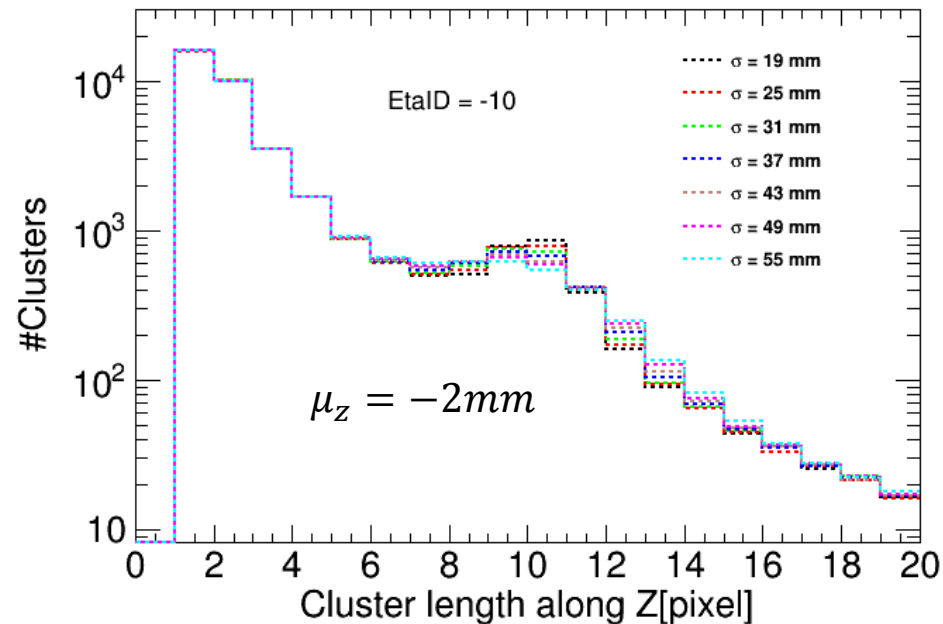
# How to describe the backgrounds?

- Backgrounds source
  - Secondary clusters from the interaction of primaries with the material
    - Template derived from MC
  - “Afterglow”: delayed tails of the particle cascade produced in the detector material
    - Exponentially falling
    - No simulation of the exponential afterglow in MC
- How to get the template of the secondary clusters
  - All clusters except for those from the primary particles
  - The template of each eta ring is averaged over 14 modules in the same ring



- Fit to MC
  - Gaussian + BkgTemplate

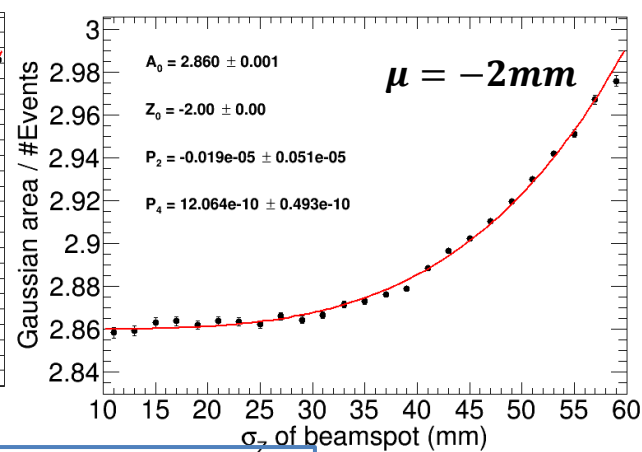
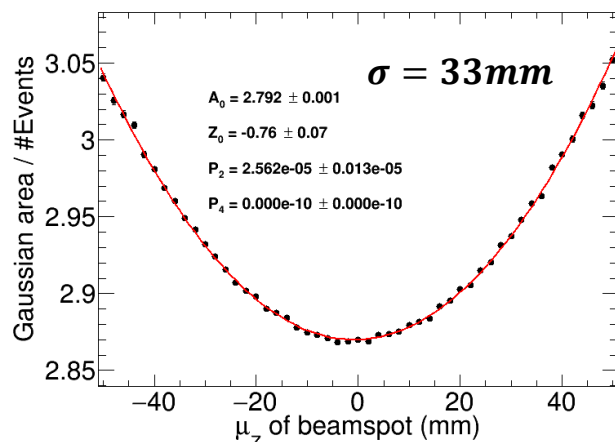
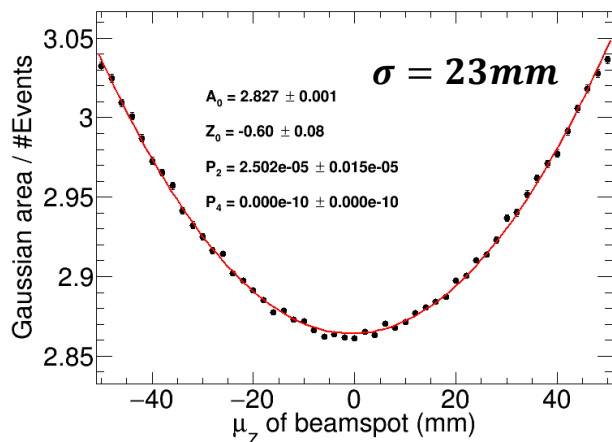
# MC-derived template depends on the beamspot shape?



- The template slightly depends on the beamspot position and width

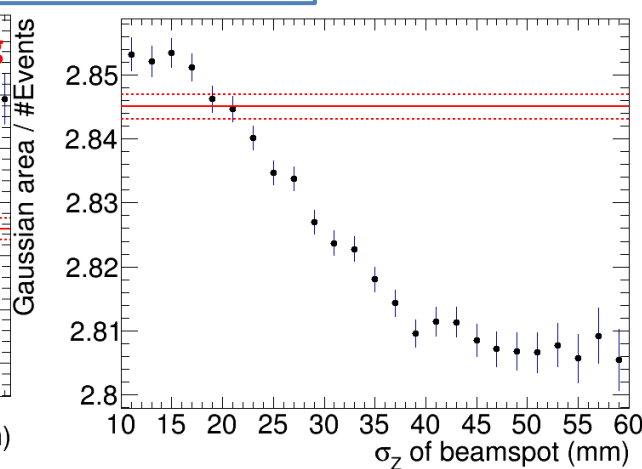
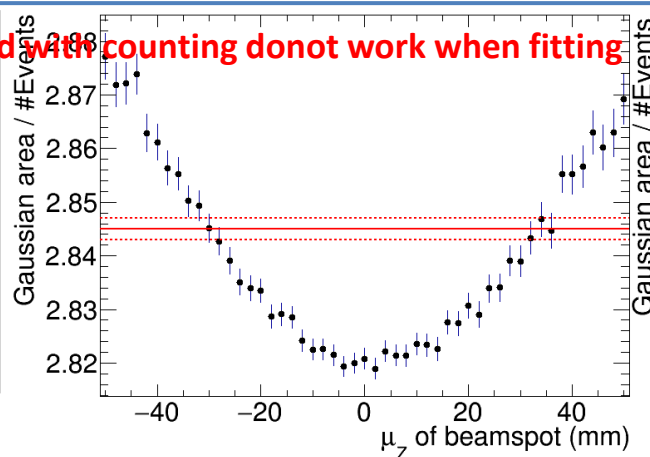
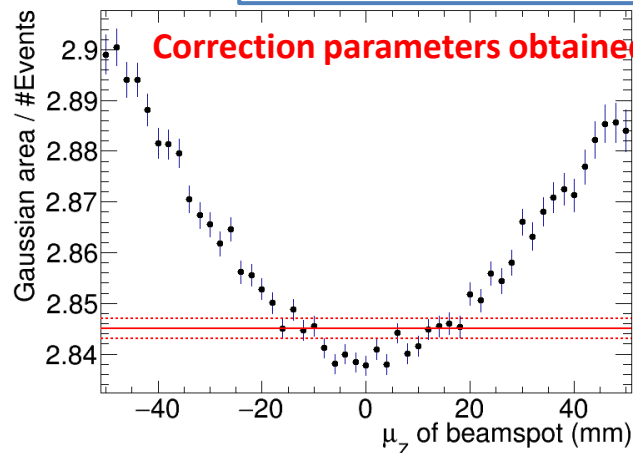


# Could Gaussian + BkgTemplate well describe MC?



$$A_0 * \left[ 1 + p_2 * \left( (\mu_z - z_0)^2 + \sigma_z^2 \right) + p_4 * \left( (\mu_z - z_0)^4 + 6\sigma_z^2(\mu_z - z_0)^2 + 3\sigma_z^4 \right) \right]$$

Correction parameters obtained with counting donot work when fitting

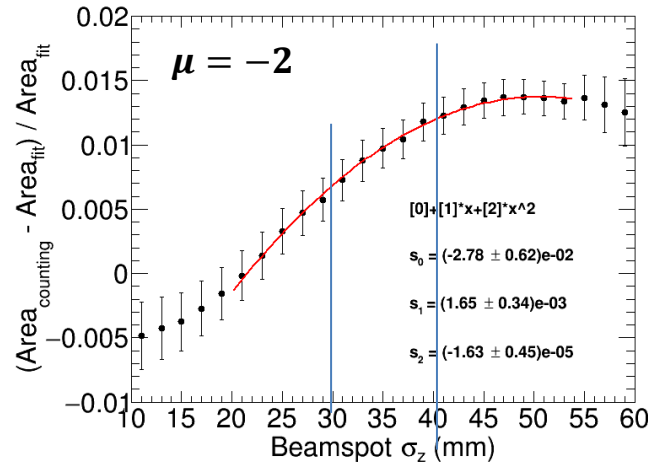
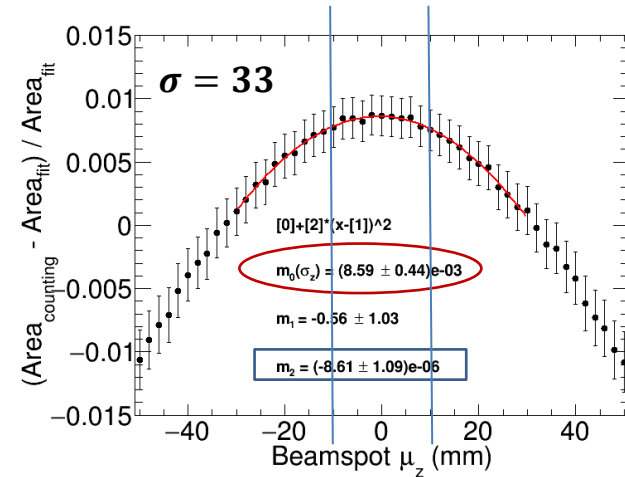
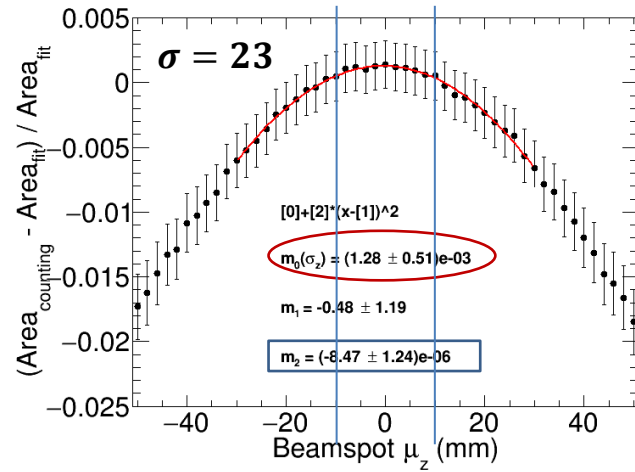


- Expected area ( $A_0$ ) and correction parameters ( $p_2, p_4$ ) obtained with different samples are not consistent
  - Due to the BS shape dependence of the BkgTemplate or the flat tail of signal?
  - Deviation of the fit result relative to counting result  $\frac{\text{Area}_{\text{counting}} - \text{Area}_{\text{fit}}}{\text{Area}_{\text{fit}}}$

# Area<sub>counting</sub> – Area<sub>fit</sub> Area<sub>fit</sub>

$$\frac{Area_{counting} - Area_{fit}}{Area_{fit}} =$$

$$m_0(\sigma_z) + m_2(\mu_z - z_0)^2$$



$$m_0(\sigma_z = 23) = 1.38e - 03$$

$$m_0(\sigma_z = 33) = 8.72e - 03$$

$$\diamond Area_{counting} = Area_{fit}(1 + s_0 + s_1\sigma_z + s_2\sigma_z^2 + m_2(\mu_z - z_0)^2)$$

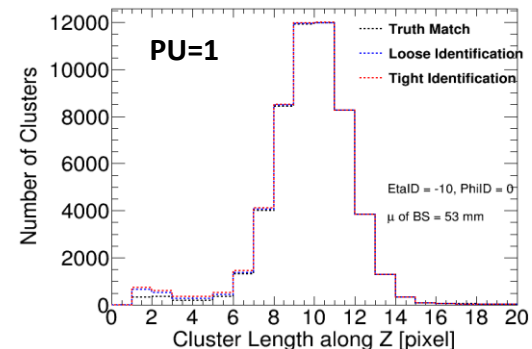
- $m_0(\sigma_z)$  obtained in the top two plots are consistent with those in the bottom plot
- $m_2$  obtained in the top two plots are consistent with each other

# Preparation work before the study of real data

- To validate the correction in real data
  - Need to filter out the cluster on module edge and broken clusters
  - “eta\_pixel\_index” and “phi\_pixel\_index” are necessary to identify the broken clusters. But these two variables are missing in the reconstruction of 2016 data to save space
  - Check how larger the DAOD\_IDPIXLUMIFile would be after including these two variables
    - Working on 21.0 which is dedicated to 2017 data
    - Adding "eta\_pixel\_index" and "phi\_pixel\_index" has lead to 9.1% increase of the DAOD\_IDPIXLUMIFile
  - Ongoing: “Flag\_edge” “Flag\_broken” → reduce space occupancy

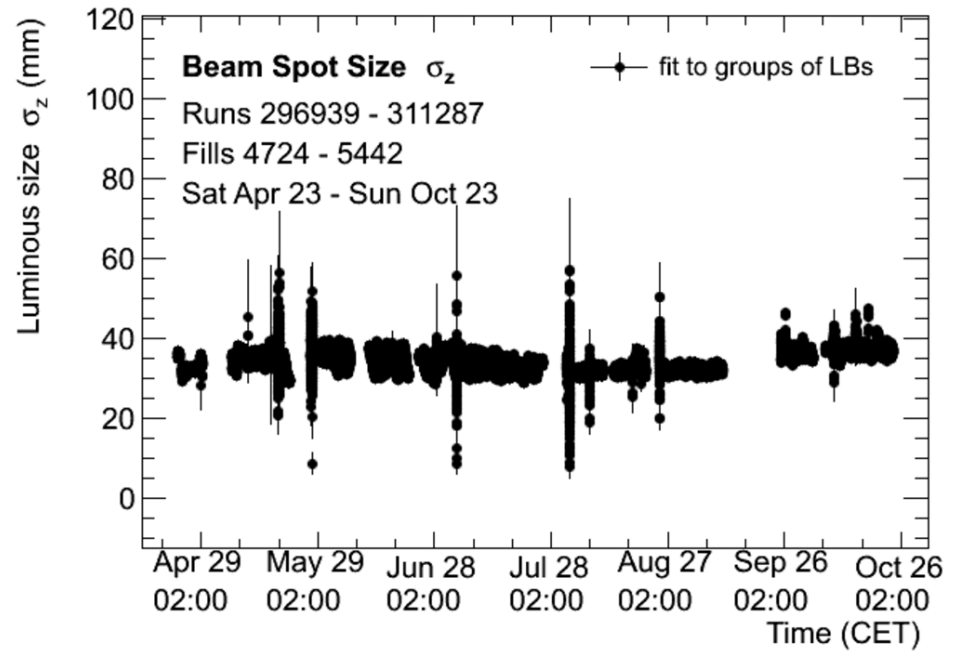
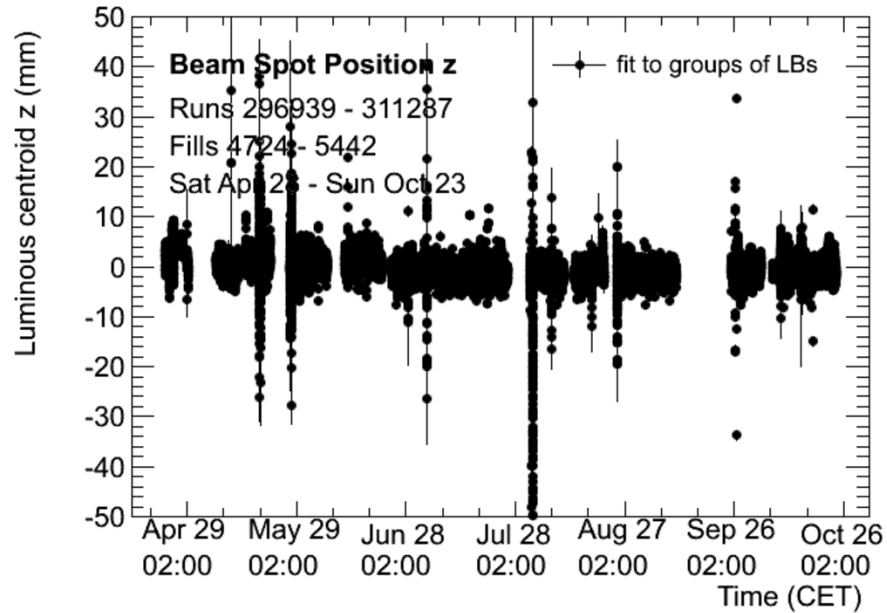
# Need to do

- “afterglow” exponentially falling?
  - Run 276073 has several empty bunch crossings.
  - Separate study of clusters from “afterglow” (BCID after the filled BCID)
- Tail of cluster length even after filtering out on-edge clusters and broken ones
- Could the MC-derived template of secondaries describe the real data?
- Could the fraction of secondaries and “afterglow” be well determined?



Back up

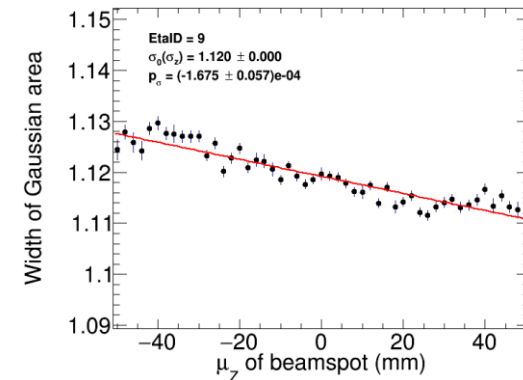
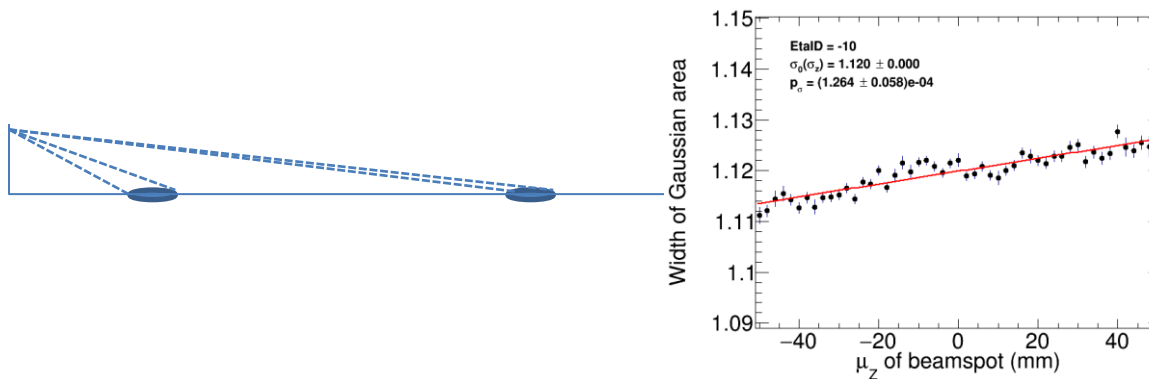
# Data2016 13TeV



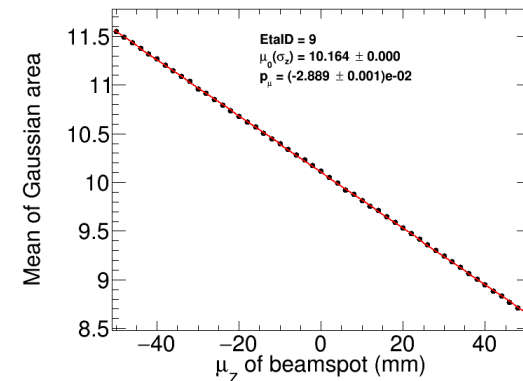
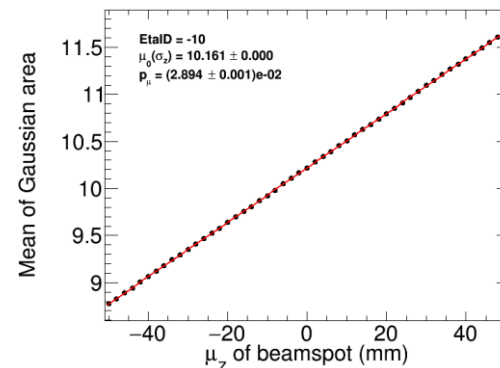
Fix the Gaussian parameters by the fit to clusters  
from primary particles?

$$\sigma_z = 33\text{mm}, \mu_z = -50, -48, -46 \dots 50\text{mm}$$

- Width of area ( $\sigma_A$ ) depends on both the location and width of beamspot:  $\sigma_A = \sigma_0(\sigma_z) + p_\sigma * (\mu_z + 2)$ 
  - $\sigma_0(\sigma_z)$  is only related to the beamspot width ( $\sigma_z$ )
  - $\sigma_A$  also depends on the beamspot location ( $\mu_z$ ) because of the different acceptance



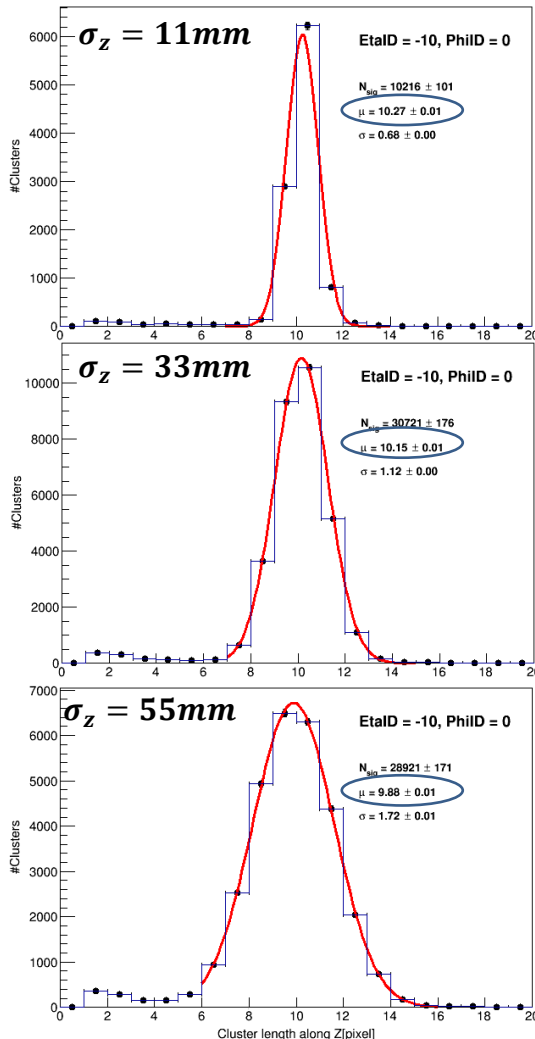
- Mean of area depends on both the location and width of beamspot:  $\mu_A = \mu_0(\sigma_z) + p_\mu * (\mu_z + 2)$ 
  - $\mu_0$  only depends on the module position? It turns out  $\mu_0$  also depends on  $\sigma_z$  (see next page)



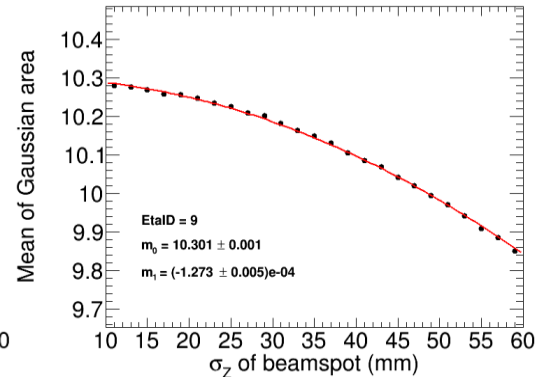
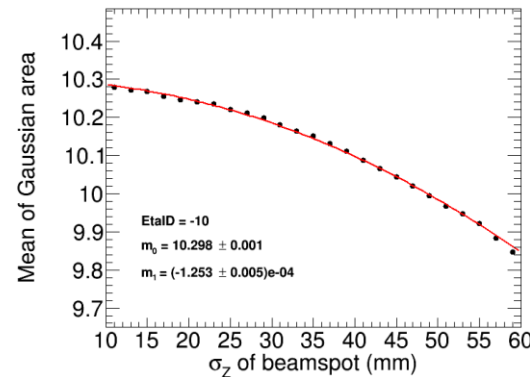


$$\mu_z = -2\text{mm}, \sigma_z = 11, 13, 15 \dots 59\text{mm}$$

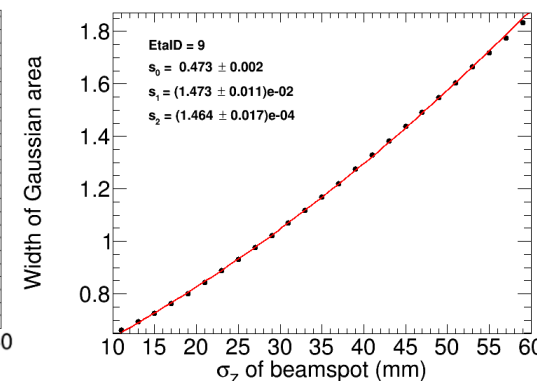
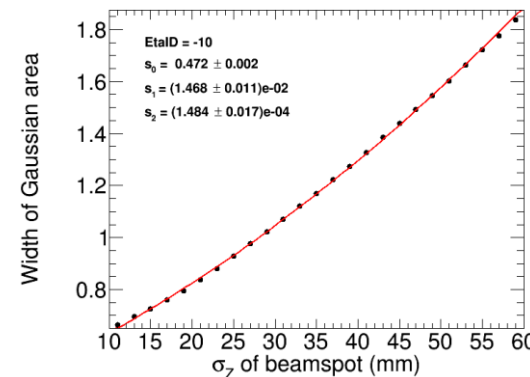
- Mean of the Gaussian area is expected **not** to depend on  $\sigma_z$ , but it actually is.
  - Due to the remaining flat structure on the left?



$$\checkmark \mu_0(\sigma_z) = m_0 + m_1 * \sigma_z^2$$



$$\checkmark \sigma_0(\sigma_z) = s_0 + s_1 * \sigma_z + s_2 * \sigma_z^2$$



# beamspot shape dependence of the Gaussian area shape

- $$\begin{aligned} \sigma_A &= \sigma_0(\sigma_z) + p_\sigma * (\mu_z + 2) \\ \sigma_0(\sigma_z) &= s_0 + s_1 * \sigma_z + s_2 * \sigma_z^2 \end{aligned} \quad \left. \vphantom{\begin{aligned} \sigma_A &= \sigma_0(\sigma_z) + p_\sigma * (\mu_z + 2) \\ \sigma_0(\sigma_z) &= s_0 + s_1 * \sigma_z + s_2 * \sigma_z^2 \end{aligned}} \right\} \sigma_A = (s_0 + s_1 * \sigma_z + s_2 * \sigma_z^2) + p_\sigma * (\mu_z + 2)$$

- $$\begin{aligned} \mu_A &= \mu_0 + p_\mu * (\mu_z + 2) \\ \mu_0 &= m_0 + m_1 * \sigma_z^2 \end{aligned} \quad \left. \vphantom{\begin{aligned} \mu_A &= \mu_0 + p_\mu * (\mu_z + 2) \\ \mu_0 &= m_0 + m_1 * \sigma_z^2 \end{aligned}} \right\} \mu_A = (m_0 + m_1 * \sigma_z^2) + p_\mu * (\mu_z + 2)$$

- How to determine the parameters has been shown in the fits in last two pages
  - $\mu_A$  and  $\sigma_A$  have been averaged over all modules in the same eta ring
  - The parameters are different for different eta rings (refer to the fits in following pages). The parameters of the symmetric eta rings have been averaged.